



# Deterministic Design Optimization of Structures in OpenMDAO Framework

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14<sup>th</sup> AIAA/ISSMO Multidisciplinary Analysis Optimization  
Conference  
Indianapolis, Indiana

17-19 September 2012

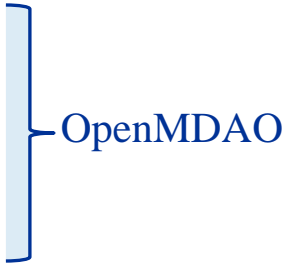


# Acknowledgement

- Funded by the Fixed Wing Project under the NASA Fundamental Aeronautics Program



# Overview

- Development of OpenMDAO Framework led out of NASA Glenn Research Center with support from NASA Langley Research Center
  - Can be used to develop an integrated analysis, optimization and design environment for engineering challenges. Hosting site: <http://openmdao.org>
- Demonstrate and verify OpenMDAO implementation by analyzing a set of widely used benchmark structural design problems and realistic cases
- Nonlinear Optimization Programming Techniques
  - NEWSUMT
  - CONMIN
  - NLPQL
  - Ipopt
  - NSGA-IIA light blue vertical bracket groups the five optimization techniques listed to its left. To the right of the bracket, the text "OpenMDAO" is written in a dark blue serif font.

OpenMDAO
- Compare results of OpenMDAO with CometBoards (Comparative Evaluation Test Bed of Optimization and Analysis Routines for the Design of Structures)
- Summary and Future Plans

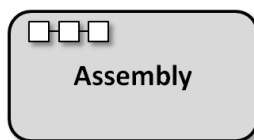


# Basic Features



- OpenMDAO is an open source framework, easily available on <http://openmdao.org>
- Based on Python programming language; high level, interpreted language
- Provides a common platform to develop, test, and apply state-of-the-art optimization techniques for analyzing/optimizing MDAO problems
- Users can solve complex problems by linking together analysis and optimization codes from multiple disciplines & multiple architectures
- Structural Analysis Discipline: MSC/NASTRAN & closed form analysis
- Optimization Capabilities: Single-objective, Multi-Objective Techniques & Cascade Strategy
- Stochastic Optimization Capability: NESSUS/FPI - Initial version
- OpenMDAO is flexible and robust because it separates the flow of information (dataflow) from the process in which analyses are executed (workflow)

**Component** – a computational engineering application that accepts input and returns output



**Assembly** – a container object which houses sub-components, defining data connections between them

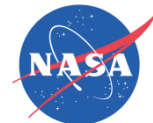


**Driver** – an object that controls process iteration (solvers, optimizers, iterators, etc.)



**Workflow** – an object that specifies execution order of components for a driver

Ref. Kenneth T. Moore, "OpenMDAO Development and Usage", July 2012



# OpenMDAO: Components (Solvers) Drivers (Optimizers) and Plugin Library

## Components:

- adpac\_wrapper
- excel\_wrapper
- flops\_wrapper
- **nastran\_wrapper**
- nessus\_stochastic
- ommodel\_wrapper
- overflow\_wrapper
- pareto\_filter
- pdcyl\_comp
- vsp\_wrapper

## Drivers:

- COBYLA
- **CONMIN**
- DOE
- FixedPointIterator
- Genetic
- **Ipopt**
- **NEWSUMT**
- **NLPQL**
- **pyOpt**
- Sensitivity
- SLSQP

## Other Plugins:

### Surrogate Models:

- Neural\_net

### DOE Generators:

- Monte Carlo

### Resource Allocators:

- NAS\_access

### Differentiators:

- Chain Rule
- Analytic
- **Finite Difference**

- Users Guide and Developers Guide Documentation; Forum; Screenscasts; Cookbook; Publications
- Plugin Installation Tool
- All of the official plugins can be found at: <https://github.com/OpenMDAO-Plugins>
- Users are encouraged to contribute their own plugins as well



# Deterministic Design Optimization

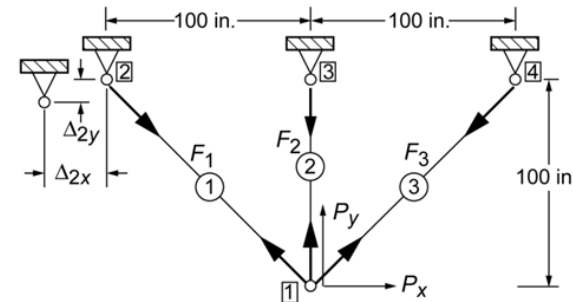
- Casted as a nonlinear mathematical programming problem:  
Find  $x$  that minimizes  $W(x)$  subject to  $\mathbf{g}(x) \leq \mathbf{0}$ ,  $\mathbf{h}(x) = \mathbf{0}$  and  $x_{lb} \leq x \leq x_{ub}$   
where  $W$  is an objective,  $x$  is a vector of design variables,  $\mathbf{g}$  is a vector of inequality constraints,  $\mathbf{h}$  is a vector of equality constraints, and  $x_{lb}$  and  $x_{ub}$  are vectors of lower and upper bounds on the design variables.
- Applications of nonlinear programming include: aerospace engineering, aircraft and spacecraft design, automobile design, naval architecture, electronics, computers, etc.
- Component used in OpenMDAO Framework:
  - MSC/NASTRAN is the analyzer
- Optimizers used in OpenMDAO Framework:
  - 1) NEWSUMT – Sequence of Unconstrained Minimizations Technique - *Miura, H. and Schmit, L. A. Jr.*
  - 2) CONMIN – CONstraint function MINimization - *Vanderplaats, G.N.*
  - 3) NLPQL – Non-Linear Programming by Quadratic Lagrangian - *Schittkowski, K.*
  - 4) Ipopt – Interior Point OPTimizer - <https://projects.coin-or.org/Ipopt>
  - 5) NSGA-II – Nondominated Sorting Genetic Algorithm - *Deb K.*
- CometBoards (NEWSUMT)



# Description and Results of Demonstration Cases

# Case 1: Optimization of a Three-Bar Truss

- Design Variables:
  - Areas of the three rod elements
- Objective:
  - Minimize the weight of the truss
- Constraints:  $|\sigma_i| \leq \sigma_{allow} \quad i = 1, 2, 3$   
 $\delta_i \leq \delta_{max} \quad i = 1, 2$



OpenMDAO Model Variables Specification			
Variable Name	Data type	Default Value, I/O type	Description, Units
bar1_area	Float	0.0, input	cross-sectional area for bar1, inch*inch
bar2_area	Float	0.0, input	cross-sectional area for bar2, inch*inch
bar3_area	Float	0.0, input	cross-sectional area for bar3, inch*inch
bar1_stress	Float	0.0, output	stress in bar1, lb/(inch*inch)
bar2_stress	Float	0.0, output	stress in bar2, lb/(inch*inch)
bar3_stress	Float	0.0, output	stress in bar3, lb/(inch*inch)
displacement_x_dir	Float	0.0, output	displacement in x_direction, inch
displacement_y_dir	Float	0.0, output	displacement in y_direction, inch
weight	Float	0.0, output	weight of the structure, lbs





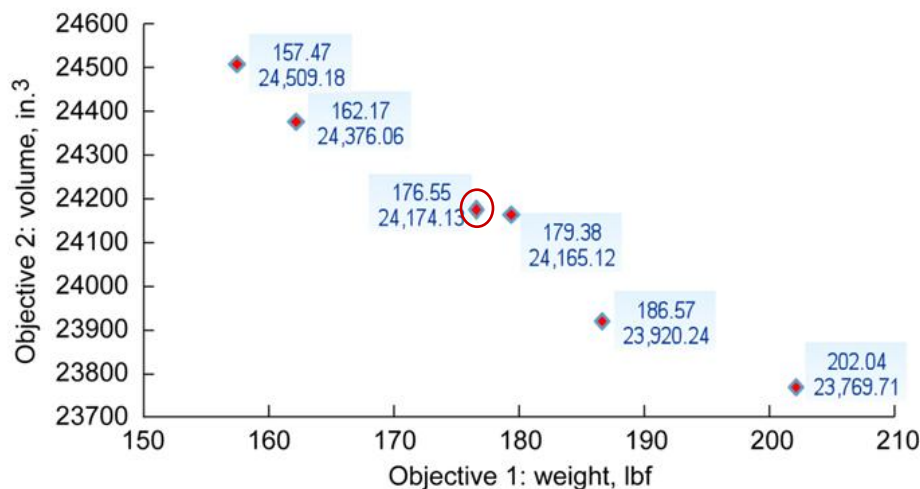
# Three-Bar Truss Results

Problem	OpenMDAO Optimization Methods				CometBoards (NEWSUMT)
	NEWSUMT	CONMIN	NLPQL	Ipop	
<b>3-bar truss</b> Design variables:3 Constraints: 3S, 2D					
<b>Optimal Weight, lb</b>	237.115	237.151	237.101	237.357	237.194
<b>Optimal Design(in<sup>2</sup>):</b>	3.5356	3.5343	3.5330	3.5346	3.5334
	3.3382	3.3380	3.3380	3.3425	3.3394
	0.0101	0.01	0.0100	0.0116	0.0105
<b>Active Constraints</b> S: Stress; D: Displacement	1S, 1D	1S, 1D	1S, 1D	1S,1D	1S,1D
<b>Number of Iterations</b>	33	17	9	101	31
<b>CPU time (mins)</b>	33.191	6.183	4.231	93.320	180.0

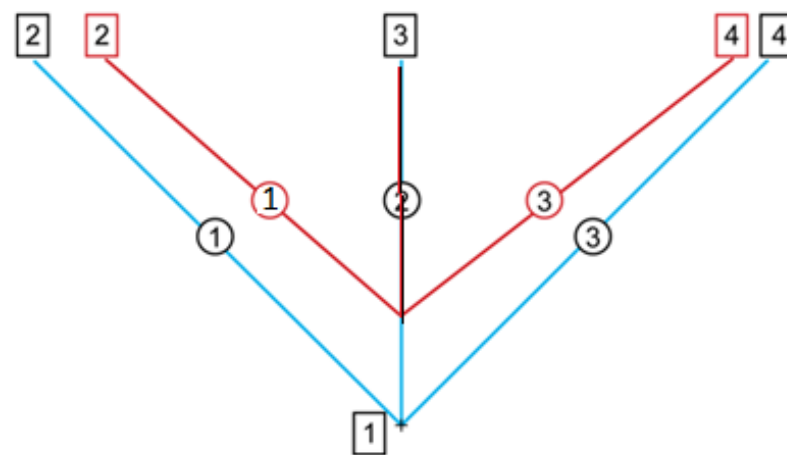
- Variation in solutions: Weight: 0.03% (NLPQL) to 0.07% (Ipop)
- CPU time: NLPQL 42 times faster than CometBoards with fewer iterations
- OpenMDAO NEWSUMT reduced solution time by a factor of 5.4
- Performance: Acceptable by all methods

# Multi-Objective Shape Optimization of the Static 3-Bar Truss

- Objective 1: Minimize the weight
- Objective 2: Minimize the enclosed volume
- Design Variables: cross-sectional areas of the bars, position of node 1 (y-dir), position of nodes 2 and 4 (x-direction)
- Behavior constraints: stress and displacements
- NSGA-II Algorithm: population size = 80; generations = 50; crossover probability = 1.0; mutation probability = 0.5; distribution index = 20 and 50



Pareto optimal front for the 3bar truss



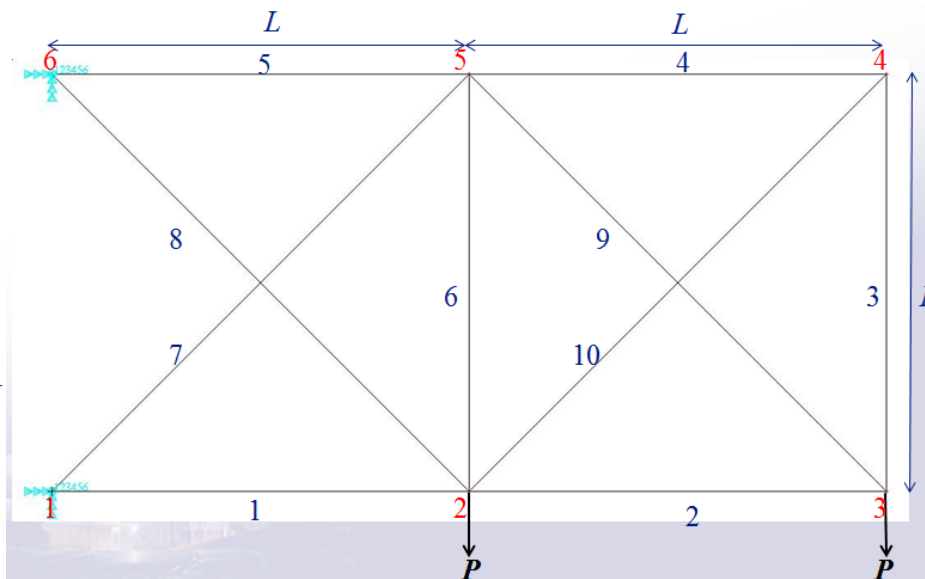
Initial (blue) and optimal shape (red)

# Case 2: Design of a Ten-Bar Truss

- **Objective:**  
Minimize the weight of the truss
- **Design Variables:**  
Areas of the ten rod elements
- **Constraints:**

$$|\sigma_i| \leq \sigma_{allow} \quad i = 1, 10$$

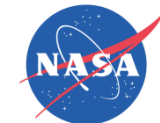
$$\delta_i \leq \delta_{max} \quad i = 1, 2$$



$$\begin{aligned} L &= 360 \text{ inch} \\ P &= 100 \text{ kips} \\ E &= 10 \text{ Msi} \\ \rho &= 0.1 \text{ lb/in}^3 \\ \sigma_{allow} &= 25 \text{ ksi} \\ \delta_{max} &= 2 \text{ inch} \end{aligned}$$

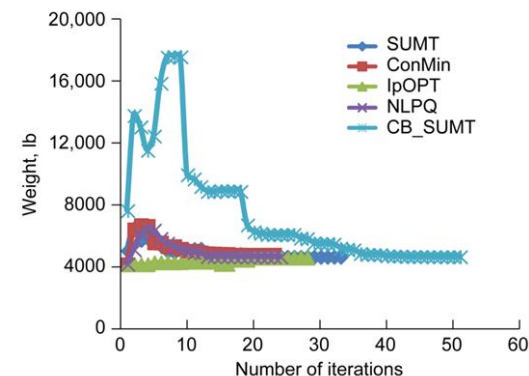
**OpenMDAO Model Variables Specification**

Variable Name	I/O Type	Data type; Description	Units	MDAO Type
bar_i_area, i = 1 to 10	input	Float; Cross-sectional area for bar_i	inch <sup>2</sup>	Design variable
bar_i_stress, i = 1 to 10	output	Float; stress in bar_i	psi	Constraint
displacement1_y_dir	output	Float; displacement in y_direction, POINT ID:3	inch	Constraint
displacement2_y_dir	output	Float; displacement in y_direction, POINT ID:4	inch	Constraint
weight	output	Float; Weight of the structure; float	lbs	Objective



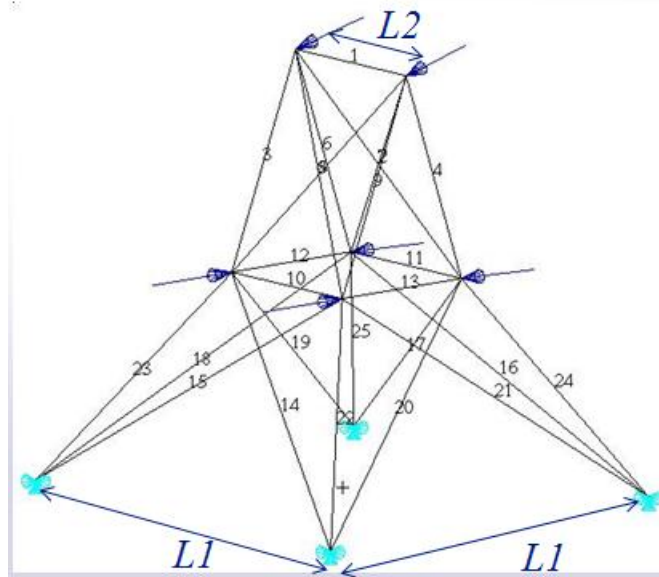
# Ten-Bar Truss Results

Optimizers	Weight, lb	Design variables, sq. in.			Active constraints		CPU, min.
		Mean value	Variation		Stress	Disp.	
			Min.	Max.			
NEWSUMT	4677.48	11.15	0.10	25.22	2	1	92.36
CONMIN	4806.92	11.48	0.10	27.99	1	1	19.05
NLPQL	4673.89	11.13	0.10	26.06	2	1	27.0
Ipopt	4620.88	11.06	9.94	13.48	Infeasible	---	67.44
CometBoards (NEWSUMT)	4678.36	11.10	0.10	25.28	2	1	600.0



- Variation in solutions : Weight: -0.09% (NLPQL) to 2.7% (CONMIN)
- Design: Infeasible for Ipopt
- CPU time: CONMIN 32 times faster than CometBoards but heavier
- OpenMDAO NEWSUMT reduced solution time by a factor of 6.5
- Performance: Acceptable by 3 methods (NEWSUMT, CONMIN, NLPQL)

# Case 3: Design of a 25-Bar Antenna Tower Truss



$$\begin{aligned}
 L1 &= 200 \text{ inch} \\
 L2 &= 75 \text{ inch} \\
 E &= 10 \text{ Msi} \\
 \rho &= 0.1 \text{ lb/in}^3 \\
 \sigma_{\text{allow}} &= 40 \text{ ksi} \\
 \delta_{\text{max}} &= \pm 0.35 \text{ inch}
 \end{aligned}$$

- Objective:  
Minimize the weight of the truss
- Linked Design Variables:  
Areas of the 8 rod elements
- Constraints:  
8 stress and 2 nodal displacement constraints on element 1

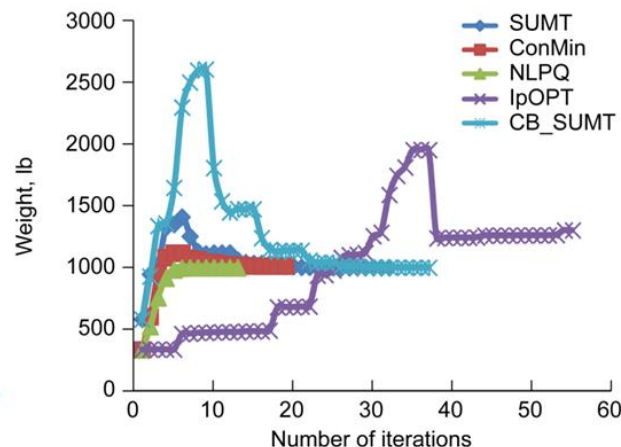
Linking of the design variables

Problem	Design variable	Members grouped
25-bar antenna tower (8LDV)	1	1
	2	2,3,4,5
	3	6,7,8,9
	4	10,11
	5	12,13
	6	14,15,16,17
	7	18,19,20,21
	8	22,23,24,25



# Results of a 25-Bar Antenna Tower Truss

Problem	OpenMDAO Optimization Methods				CometBoards (NEWSUMT)
<b>25-bar antenna tower</b> Design variables: 8 LDV Constraints: 8S, 2D	NEWSUMT	CONMIN	NLPQL	Ipopt	
<b>Optimal Weight, lb</b>	998.194	1011.804	998.084	1301.144	998.482
<b>Optimal Design (in<sup>2</sup>):</b>					
	0.3015	0.6688	0.3070	1.3877	0.2992
	2.8265	3.2492	2.8287	6.4425	2.8280
	5.4753	5.2978	5.4726	4.9730	5.4766
	1.8049	1.9988	1.8091	5.2028	1.8136
	0.1119	0.7026	0.1199	1.5624	0.1175
	2.9120	2.8756	2.9104	3.3168	2.9109
	2.9482	2.7997	2.9450	3.2615	2.9477
	3.0179	2.9805	3.0182	3.0693	3.0194
<b>Active Constraints</b> S:Stress; D:Displacement	5S	5S	5S	Infeasible	6S
<b>Number of Iterations</b>	32	17	13	58	37
<b>CPU time (mins)</b>	62.718	12.337	26.9	133.731	397.0

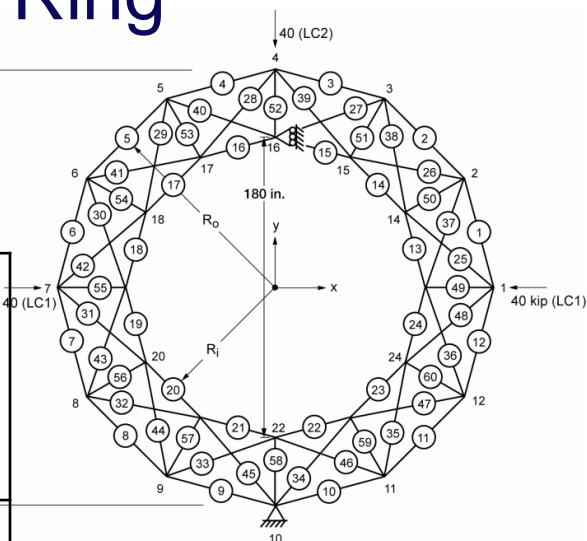


- Variation in solutions : Weight: -0.04% (NLPQL) to 1.33% (CONMIN)
- Design: Infeasible for Ipopt
- CPU time: CONMIN was 32 times faster than CometBoards but heavier
- OpenMDAO NEWSUMT reduced solution time by a factor of 6
- Performance: Acceptable by 3 methods (NEWSUMT, CONMIN, NLPQL)

## Case 4: Sixty-Bar Trussed Ring

- Objective: Minimize the weight of the truss
- The 60 areas were linked into 25 variables
- 25 stress and 24 displacement constraints

Optimizers	Weight, lbs	Design variables, sq. in.			Active constraints		CPU, <sup>200</sup> in. min.
		Mean value	Variation		Stress	Disp.	
			Min.	Max.			
NEWSUMT	308.62	1.24	0.5	2.03	12	1	123.28
CONMIN	312.75	1.21	0.5	2.02	1	1	43.93
NLPQL	308.55	1.24	0.5	2.03	12	1	59.0
Ipopt	340.02	1.36	0.55	2.23	1	1	764.67
CometBoards (NEWSUMT)	308.67	1.24	0.5	2.03	12	1	810.0

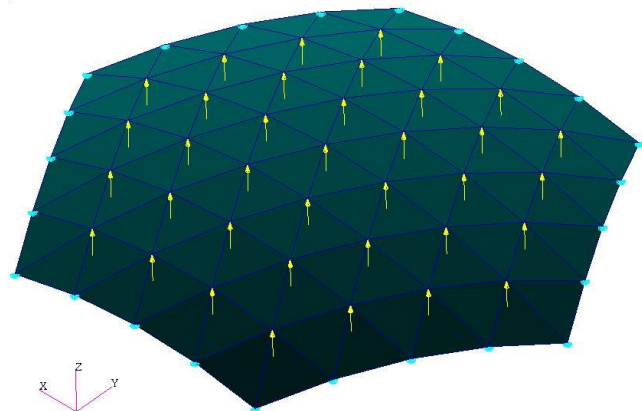


$$\begin{aligned}
 R_i &= 90 \text{ inch} \\
 R_o &= 100 \text{ inch} \\
 E &= 10 \text{ Msi} \\
 \rho &= 0.1 \text{ lb/in}^3
 \end{aligned}$$

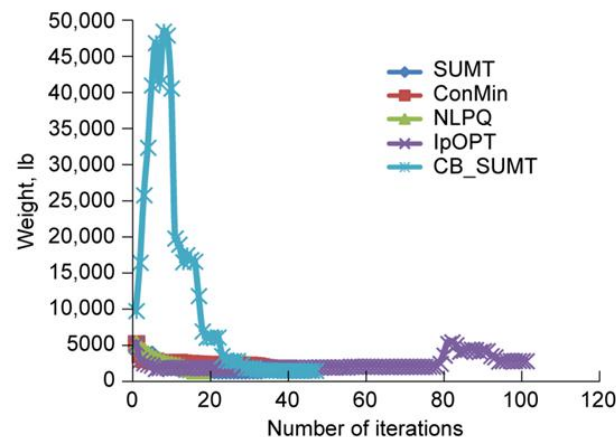
- Variation in weight about 10% (Ipopt)
- CONMIN least CPU but heavier and fewer number of active constraints
- OpenMDAO NEWSUMT reduced solution time by a factor of 6.5
- Performance: Acceptable by all methods

# Case 5: Optimization of a Membrane Structure (Geodesic Dome)

Problem	OpenMDAO Optimization Methods				CometBoards (NEWSUMT)
<b>Geodesic dome</b> Design variables: 12LDV Constraints: 252S, 1D	NEWSUMT	CONMIN	NLPQL	Ipopt	
<b>Optimal Weight, lb</b>	1539.597	1929.653	1539.517	2229.409	1540.02
<b>Optimal Design (in<sup>2</sup>):</b>	0.3015	0.6688	0.3070	1.3877	0.2992
	2.8265	3.2492	2.8287	6.4425	2.8280
	5.4753	5.2978	5.4726	4.9730	5.4766
	1.8049	1.9988	1.8091	5.2028	1.8136
	0.1119	0.7026	0.1199	1.5624	0.1175
	2.9120	2.8756	2.9104	3.3168	2.9109
	2.9482	2.7997	2.9450	3.2615	2.9477
	3.0179	2.9805	3.0182	3.0693	3.0194
<b>Active Constraints</b>	120 S	Infeasible	119 S	Infeasible	120 S
<b>Iterations</b>	33	38	17	111	48
<b>CPU time (mins)</b>	79.753	39.315	26.0	390.488	643.0



$D = 240$  inch;  $H = 30$  inch;  $P = 925$  kip  
 Bars = 156; Triangular = 96



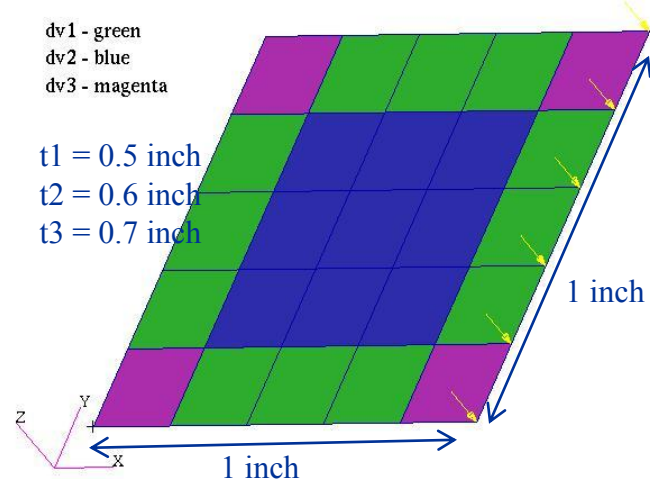
- Variation in solutions : Weight: -0.02% (NLPQL)
- Design: Infeasible for CONMIN & Ipopt
- CPU time: NLPQL 26 times faster than CometBoards and lighter design
- OpenMDAO NEWSUMT reduced solution time by a factor of 8



# Case 6: Optimization of a Composite Plate with Strain and Displacement Constraints

Problem	OpenMDAO Optimization Methods				
<b>Composite plate</b> Design variables: 3LDV Constraints: 3Strain, 1D	<b>NEWSUMT</b>	<b>CONMIN</b>	<b>NLPQL</b>	<b>Ipopt</b>	<b>CometBoards (NEWSUMT)</b>
<b>Optimal Weight, lb</b>	0.146	0.146	0.146	0.201	0.146
<b>Optimal Design, (in<sup>3</sup>):</b>	2.6829 2.4288 3.0934	2.7137 2.4066 3.0920	2.6782 2.4332 3.0921	4.6486 3.1416 1.7898	2.6819 2.4308 3.0935
<b>Active Constraints</b>	3Strain, 1D	3Strain, 1D	3Strain, 1D	Infeasible	3Strain, 1D
<b>Iterations</b>	30	8	16	36	45
<b>CPU time (mins)</b>	51.49	2.74	15.0	35.72	193.0

- Variation in solutions
  - Weight: no variation
  - Design: Infeasible for Ipopt
- CONMIN faster convergence by 98%
- Performance acceptable by 3 methods

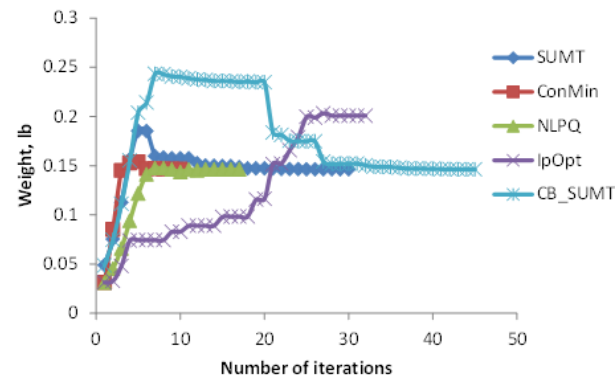


Ply lay-up: [0/-45/45/0]

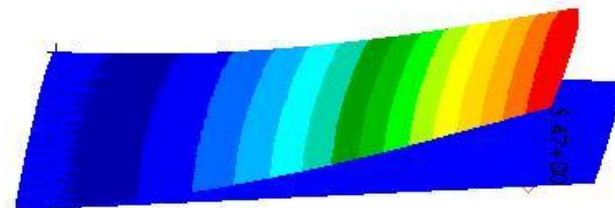
Material: graphite/epoxy tape

$$\epsilon_{\text{allow}} = 4 \times 10^{-3} \mu\text{s}$$

$$\delta_{\text{max}} = \pm 0.04 \text{ inch}$$



# Case 7: Minimize the Weight of a Ceramic Matrix Composite Blade



CQUAD4= 25,945; Nodes = 26,026; DOF = 129,330; RPM = 8490

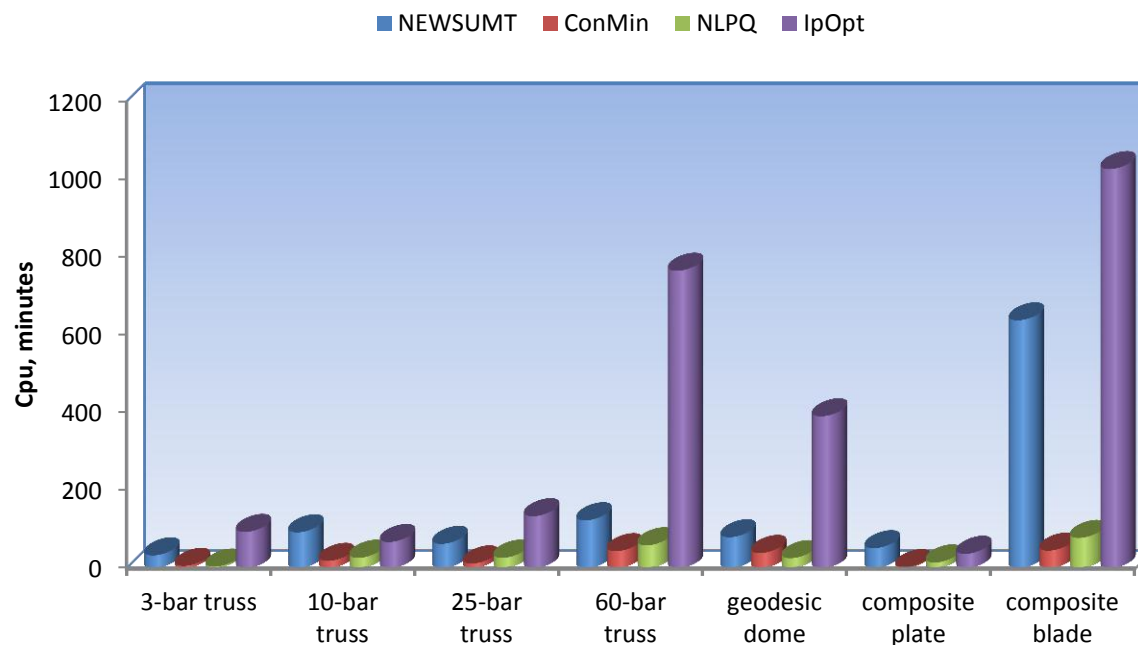
Fundamental mode shape on the deformed mesh

Design	Weight (lbs.)	Fund. Freq. (Hz)	dv1(in <sup>3.</sup> ) cap	dv2 (in <sup>3.</sup> ) wall	Iter	CPU (min)
Initial	0.123	13.48	0.5	0.03		
NEWSUMT	0.037	15.98	0.01	0.01	36	637.2
CONMIN	0.037	15.98	0.01	0.01	5	45.26
NLPQL	0.037	15.97	0.01	0.01	4	78.02
Ipopt	0.037	15.98	0.01	0.01	30	1026.26

- Increase of 18.5 % in the fundamental frequency is achieved while the weight is minimized by 70%



# CPU Comparison for the Seven Cases



	NEWSUMT	CONMIN	NLPQL	Ipopt	CometBoards
Average (minutes/iteration)	4.5	2.0	4.1	7.4	11.2
Minimum	1.0	0.3	0.5	0.9	4.3
Maximum	17.7	9.1	19.5	34.2	21.3
Improvement factor	8.1	70.5	42.5	8.9	1.0

- Average solution time is in favor of CONMIN followed by NLPQL



## Summary & Future Plans

- All four optimizations methods in OpenMDAO Framework produced acceptable solutions with some variation which may be due to the setting of the parameters and control options of the optimizers
- Overall, variation of weight was modest for all methods. Number of Active constraints was almost identical for NEWSUMT and NLPQL, but Ipopt produced infeasible designs for 4 problems
- Computing time of OpenMDAO optimizers was improved drastically by up to 87% difference in CPU time for NEWSUMT for the geodesic dome and 96% for NLPQL. Overall, OpenMDAO NEWSUMT reduced solution time by a factor of 8
- Future plans: Use OpenMDAO Framework for Stochastic Analysis of the MMSEV (Multi Mission Space Exploration Vehicle)

